

Amendments to the Specification:

Please amend numbered paragraph [0020], as shown below:

A second sensor 50, also in communication with the PCM 46, is configured to measure the velocity of the first motor 14. Because the first motor 14 may rotate in either one of two different directions, the sensor 50 must measure not only the speed of rotation, but also the direction of rotation. Similarly, a third sensor 52, also in communication with the PCM 46, is configured to measure both the speed and direction of rotation of the second motor 16--i.e., the sensor 52 measures the velocity of the second motor 16. Fourth and fifth ~~sensor~~ sensors 54,56, similarly in communication with the PCM 46, are configured to measure the speed of the wheels 36.